# Introduction to Dataflow Analysis

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GCC & GNU Toolchain Developers' Summit 2006



### Roadmap

- Introduction
- Live Variables Working Example
- Solving Dataflow Equations Efficiently
- Common Dataflow Problems
- Incremental Analysis
- Other Dataflow Problems



#### This is a Tutorial

- Feel free to ask questions at any time.
- Nothing new is going to be presented.
  - 80% of this talk was old news in 1980.
  - 95% of this talk was old news in 1985.
- I only had a little bit to do with developing dataflow analysis.
- All of the material presented except the incremental dataflow information should be any good compiler text book.
- There is no paper in the proceedings for this talk.



### Scope

 Most of the talk is concerned with bit vector dataflow analysis. In the literature these problems are called *rapid problems*.



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At the end of each statement, *s*, in the function *f*, what is the set of variables, *v*, that have a use that may be reached without going through a definition of *v*.

Dataflow information can be represented at the start of a statement or the end of a statement.



At the end of each statement, s, in the function f, what is the set of variables, v, that have a use that may be reached without going through a definition of v.

Global dataflow analyzes whole functions.



At the end of each statement, s, in the function f, what is the set of variables, v, that have a use that may be reached without going through a definition of v.

The domain of the problem. Common values include the set of variables, the set of definition sites, or the set of use sites.



At the end of each statement, s, in the function f, what is the set of variables, v, that have a use that may be reached without going through a definition of v.

The *gen set.* The points in the program that cause items to be added to the set.



At the end of each statement, s, in the function f, what is the set of variables, v, that have a use that may be reached without going through a definition of v.

The *kill set*. The points in the program that cause items to be deleted from sets.

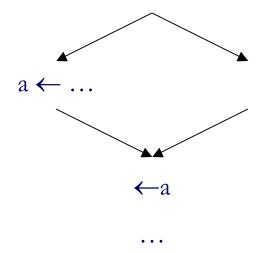


#### Direction

There are two live variables problems:

- backwards propagation proceeds against the edges in the CFG.
  - gen is the set of uses.
  - kill is the set of defs and clobbers.
  - this is what **flow** does.
- forwards propagation proceeds with the edges in the CFG.
  - gen is the set of definitions.
  - kill is the set of clobbers.
  - this is what global.c:make\_accurate\_live\_analysis does.
  - in df we call this uninitialized uses.

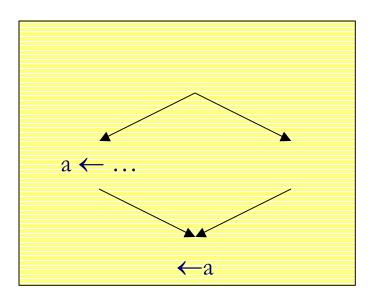








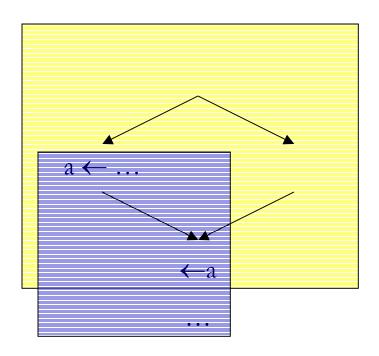
backward (flow)



. .



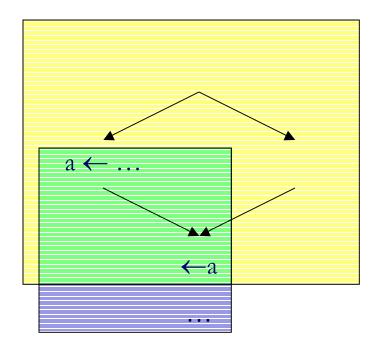
- backward (flow)
- forward (uninitialized uses)







- backward (flow)
- forward (uninitialized uses)
- forward & backward







### **Dataflow Equations**

**Backwards:** 

$$out_h = \bigcup_{s = succ (h)} in_s$$

$$in_h = out_h - kill_h + gen_h$$

$$in_h = out_h - kill_h + gen_h$$
  $out_h = in_h - kill_h + gen_h$ 

for every h in the program.

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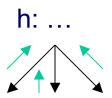


## **Dataflow Equations**

Backwards:

$$out_h = \bigcup_{s = succ (h)} in_s$$

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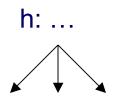


### **Dataflow Equations**

Backwards:

$$out_h = \bigcup_{s = succ (h)} in_s$$

$$in_h = out_h - kill_h + gen_h$$



Apply the effects of h.

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### **Correctness and Quality**

- A solution is correct if it satisfies the system of equations.
- For cyclic control flow graphs there are many correct solutions.
- Want to find the minimal solution.
  - For live variables this is the correct solution with the with the *fewest* 1 bits.



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### Plan I – Worklist Iteration

```
worklist ← all statements
while (worklist ≠ empty)
    h \leftarrow take from worklist
    old \leftarrow in<sub>h</sub>
    out_h \leftarrow empty
    for each s in succh
        out_h \leftarrow out_h \parallel in_s
    in_h \leftarrow (out_h \&\& \sim kill_h) || gen_h
    if (in_h \neq old)
        for each p in pred<sub>h</sub>
            add p to worklist
```

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### Plan 1.1 – Flow.c

```
worklist ← all statements
while (worklist ≠ empty)
    h \leftarrow take from worklist
    old \leftarrow in<sub>h</sub>
    out_h \leftarrow empty
    for each s in succh
        out_h \leftarrow out_h \parallel in_s
    in_h \leftarrow (out_h \&\& \sim kill_h) || gen_h|
    if (in_h \neq old)
        for each p in pred<sub>h</sub>
            add p to worklist
```

Evaluate all of the statements in a basic block at one time and in reverse order.

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### Plan 2 – Transfer Functions

- It is not necessary to apply gen and kill separately for each statement.
- Gen and kill can be computed for an entire basic block.
- For live variables:

$$gen_{s1+s2} \leftarrow (gen_{s2} - kill_{s1}) || gen_{s1}$$
  
 $kill_{s1+s2} \leftarrow (kill_{s2} - gen_{s2}) || kill_{s1}$ 

 The worklist algorithm then uses blocks rather than statements.



# Plan 3 – Elimination Algorithms

- Transfer functions can be built for other program structures than sequences of statements:
- Loops and if-then-elses can be similarly handled.
- for if-then-elses:

$$gen_{if} \leftarrow gen_{true} \parallel gen_{false}$$
  
 $kill_{if} \leftarrow kill_{true} \&\& kill_{false}$ 



### Plan 3 – Elimination Algorithms

- It is possible to parse any reducible program into sequences, simple loops and if-then-elses.
- Process the transfer functions bottom up, then top down and you have the solution.
- Multiple entry loops must be processed by iteration.
- For many years this was the method of choice because it was much faster than the worklist.
- Allen Cocke and Schwartz were the first to propose this.
- Graham and Wegman was the method of choice.



### Plan 4 – Better Worklists

- Hecht demonstrated that better management of the worklist could yield an algorithm that was just as fast as elimination algorithms.
  - For forward problems, multiple passes in reverse postorder are made.
  - For reverse problems, multiple passes in postorder are made.
- Works for all functions, even irreducible ones.
- Easy to implement.



#### Plan 4.1 – Even Better Worklists

- Atkinson and Griswold demonstrated that doing a little depth first search in the middle of Hecht's algorithm generally speeded things up.
- This is what is used in df.



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#### **Common Dataflow Problems**

- There are 5 common fast dataflow problems:
  - Live Variables.
  - Uninitialized Variables
  - Reaching Uses
  - Reaching Definitions
  - Code Placement



#### **Common Dataflow Problems**

- These problems are common because they are easy to understand and formulate for text books and student compilers.
- Real compilers have more hair:
  - subregs
  - aliasing
  - thread synchronization
- You generally can use these problems as stating points for the solution to your exact problem.

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- Backward.
- Each slot is for one variable.
- Kill = the set of variables clobbered
   + the set of variables defined at s.
- Gen = the set of variables used at s.
- Confluence = or (set union).



### **Uninitialized Variables**

- Forward.
- Each slot is for one variable.
- Kill = the set of variables clobbered at s.
- Gen = the set of variables defined at s.
- Confluence = or (set union).



### Reaching Uses

- Backward.
- One use for each slot in the bit vectors.
- Kill = if v is clobbered or defined at s add all uses of v.
- Gen = the set of uses at the statement.
- Confluence = or (set union).



### Reaching Defs

- Forward.
- One def for each slot in the bit vectors.
- Kill = if v is clobbered or defined at s add all defs of v.
- Gen = the set of defs at s.
- Confluence = or (set union).



#### Code Placement

- Originally proposed as bidirectional problem by Morel and Renvoise.
- Large number of reformulations in the literature.
- People tend to use Chow's second formulation. This is a backward problem followed by a simple forward cleanup.
- Some variant of Chow's second formulation is used in GCC.



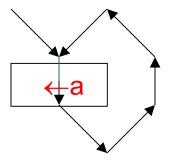
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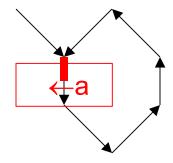


- Incremental dataflow analysis is hard:
  - It is easy to get a correct solution.
  - It is hard to get a minimal solution.

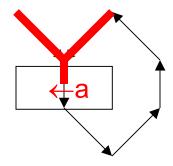




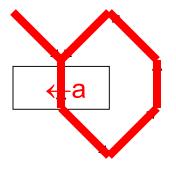






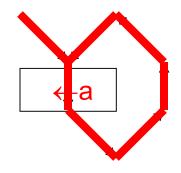






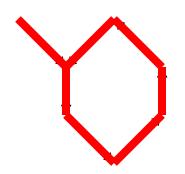


 For live variables, bits get stuck on in loops after the deletion of a bit in a gen set.





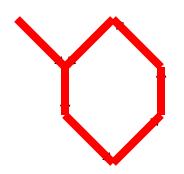
- For live variables, bits get stuck on in loops after the deletion of a bit in a gen set.
- That *in* is defined in terms of *out* and *out* is defined *in* terms of *in* of the *preds* means that it is hard to break cycles.
- This is a correct solution, just not minimal.



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- For live variables, bits get stuck on in loops after the deletion of a bit in a gen set.
- That in is defined in terms of out and out is defined in terms of in of the preds means that it is hard to break cycles.
- This is a correct solution, just not minimal.
- This is what flow does and we do not want to do this.



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- All algorithms fall into two categories:
  - Ryder: find the smallest region that encompasses all of the possible bits from the deleted gen.
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  - Ryder: find the smallest region that encompasses all of the possible bits from the deleted gen.
  - Zadeck: go after the bits one by one.
- Neither approach yielded a practical algorithm for compilers.
- I have let it go.



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#### Other Dataflow Problems

There are a lot of dataflow problems that do not fit into the rapid framework:

- You cannot build efficient transfer functions.
- The slots in the vectors are not independent.
- The values in the slots are not single bits.
- Constant Propagation.
- Alias Analysis.

